FIG. 41

ATTENT	TION PA	TTERN		SENTATI TION PA		COVERSION METHOD		
HM1	HM2	НМЗ	HM1	HM2	НМЗ	INVERSON	ROTATION	
0	0	0	0	0	0	0	0	
0	0	1	0	0	1	0	0	
0	0	2	0	0	1	11	1	
0	1	0	0	0	1	1	0	
0	1	1	0	1	1	0	0	
0	1	2	0	1	2	0	0	
0	3	0	0	0	1	0	11	
0	3	1	0	1	2	1	0	
0	3	2	0	3	2	0	0	
2	0	0	0	0	1	0	2	
2	0	1	0	1	2	1	1	
2	0	2	0	1	1	0	2	
2	1	0	0	3	2	0	1	
2	1	1	2	1	1	0	0	
2	1	2	2	1	1	1	1	
2	3	0	0	1	2	1	2	
2	3	1	2	3	1	0	0	
2	3	2	2	1	1	0	2	
3	0	0	0	0	1	1	2	
3	0	1	0	3	2	0	2	
3	0	2	0	1	2	0	2	
3	1	0	0	1	2	0	1	
3	1	1	2	1	1	1	0	
3	1	2	2	3	1	1	0	
3	3	0	0	1	1	0	1	
3	3	1	2	1	1	0	1	
3	3	2	2	1	11	1	2	

FIG. 42

GP	INVERSION	ROTATION	REPRESEN- TAVIVE GP	
GP1	0	0	GP1	
GP1	0	1	GP1	
GP1	0	2	GP1	
GP1	1	0	GP1	
GP1	1	1	GP1	
GP1	1	2	GP1	
GP2	0	0	GP2	
GP2	0	1	GP3	
GP2	0	2	GP4	
GP2	1	0	GP4	
GP2	1	1	GP2	
GP2	1	2	GP3	
GP3	0	0	GP3	
GP3	0	1	GP4	
GP3	0	2	GP2	
GP3	1	0	GP3	
GP3	1	1	GP4	
GP3	1	2	GP2	
GP4	0	0	GP4	
GP4	0	1	GP2	
GP4	0	2	GP3	
GP4	1	0	GP2	
GP4	1	1	GP3	
GP4	1	2	GP4	
GP5	0	0	GP5	
GP5	0	1	GP5	
GP5	0	2	GP5	
GP5	1	0	GP5	
GP5	1	1	GP5	
GP5	1	2	GP5	

FIG. 43

HM1	HM2	НМЗ	GP1	GP2	GP3	GP4	GP5
0	0	0	10034	130	375	213	3024
0	0	1	312	118	322	61383	2083
0	1	1	238	233	1183	112	31094
0	1	2	270	1231	738	337	63183
0	3	2	782	733	31782	1821	7108
2	1	1	374	1284	937	337	62198
2	3	1	144	1178	753	982	20837

FIG. 44

HM1	HM2	НМЗ	GP
0	0	0	GP1
0	0	1	GP4
0	1	1	GP5
0	1	2	GP5
0	3	2	GP3
2	1	1	GP5
2	3	1	GP5